Otto-von-Guericke-Universität Magdeburg Max-Planck-Institut for Dynamics of Complex Technical Systeme Computational Methods in Systems and Control Theory

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## Scientific Computing 2 Tutorial 1

## Exercise 1:

Given is a set of algorithms which have the following properties depending on an input of size n:

	Algorithm 1	Algorithm 2	Algorithm 3	Algorithm 4
Number of Flops	815n	$2n^2 + n$	$6n^{3}$	$15n^{3}$
Percentage of parallelizeable code	90%	99%	15%	80%

- a.) Compute the upper bounds for the speedup of all three algorithms.
- b.) Consider an input of size n = 2000 and a CPU with a performance of 5 GFlop/s. Compute the runtime and the speedup if you employ 1, 2, 4 or 8 of these CPUs in parallel.

## Exercise 2:

Consider the following pseudo code algorithms. Compute the number of performed flops in dependence of the size of the input. Think about which parts of them are parallelizeable. Use Amdahl's Law to determine the maximum theoretical speedup.

a.) The scalar (dot) product:

Input:  $x \in \mathbb{R}^n$ ,  $y \in \mathbb{R}^n$ Output:  $s = (x, y) = x^T y$ 1: s := 02: for  $i := 1, \dots, n$  do 3:  $s := s + x_i y_i$ 4: end for

b.) The general matrix-matrix product (GEMM):

```
Input: A \in \mathbb{R}^{n \times k}, B \in \mathbb{R}^{k \times m}, C \in \mathbb{R}^{n \times m}

Output: C := C + AB

1: for i := 1, \dots, n do

2: for j := 1, \dots, m do

3: for l := 1, \dots, k do

4: C_{ij} := C_{ij} + A_{il}B_{lj}

5: end for

6: end for

7: end for
```

c.) The LU decomposition without pivoting:

```
Input: A \in \mathbb{R}^{n \times n}

Output: LU := A, A is overwritten by L and U

1: for k = 1, \dots, n-1 do

2: A_{k+1:n,k} := A_{k+1:n,k}/A_{k,k}

3: A_{k+1:n,k+1:n} := A_{k+1:n,k+1:n} - A_{k+1:n,k}A_{k,k+1:n}

4: end for
```

d.) Forward substitution Lx = b (Backward substitution is the same):

**Input:**  $L \in \mathbb{R}^{n \times n}$ ,  $b \in \mathbb{R}^{n}$  **Output:**  $x \in \mathbb{R}^{n}$ ,  $x = L^{-1}b$ , b is overwritten by x1:  $b_{1} := b_{1}/L_{1,1}$ 2: **for** i := 2, ..., n **do** 3:  $b_{i} := b_{i} - L_{i,1:i-1}b_{1:i-1}$ 4:  $b_{i} := \frac{b_{i}}{L_{i,i}}$ 5: **end for** 

e.) Solving a linear system Ax = b,  $A \in \mathbb{R}^{n \times n}$ ,  $b \in \mathbb{R}^{n \times n}$  and  $x \in \mathbb{R}^{n \times n}$ . Use the *LU*-decomposition from c.) and the forward/backward substitution from d.).

## Exercise 3:

Consider the so called vector-triad benchmark:

Input:  $a, b, c, d \in \mathbb{R}^n$ Output:  $a_i = b_i + c_i d_i \quad \forall i = 1..., n$ 1: for i = 1, ..., n do 2:  $a_i := b_i + c_i d_i$ 3: end for

a.) Compute the performance (in GFlops/s) when we execute the vector-triad sequentially on a CPU with a performance of 12.8 GFlops/s for different vector lengths n:

Length $n$ of $a, b, c, d$	Runtime in s	
$n = 10\ 000$		
$n = 100\ 000$		
$n = 1\ 000\ 000$		
$n = 100\ 000\ 000$		

b.) Explain why the practical results are much different from the theoretical ones. Why does even employing a second CPU-core with an additional performance of 12.8 GFlops/s not result in a performance gain?