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Computational Methods in Systems and Control Theory

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Scientific Computing 2
Tutorial 1

Exercise 1:

Given is a set of algorithms which have the following properties depending on an input of size n:

	Algorithm 1	Algorithm 2	Algorithm 3	Algorithm 4
Number of Flops	$815n$	$2n^2 + n$	$6n^3$	$15n^3$
Percentage of parallelizeable code	90%	99%	15%	80%

a.) Compute the upper bounds for the speedup of all three algorithms.

b.) Consider an input of size $n = 2000$ and a CPU with a performance of 5 GFlop/s. Compute the theoretical runtime and the speedup if you employ 1, 2, 4 or 8 of these CPUs in parallel.

Exercise 2:

Consider the following pseudo code algorithms. Compute the number of performed flops in dependence of the size of the input. Think about which parts of them are parallelizeable. Use Amdahl's Law to determine the maximum theoretical speedup. If the algorithm seems to be strictly squential is there a possibility to easily modify it such that the parallel part of the algorithm increases?

a.) The scalar (dot) product:

Input: $x \in \mathbb{R}^n$, $y \in \mathbb{R}^n$
Output: $s = (x, y) = x^T y$

1: $s := 0$
2: **for** $i := 1, \ldots, n$ **do**
3: $\quad s := s + x_i y_i$
4: **end for**

b.) The general matrix-matrix product (GEMM):

Input: $A \in \mathbb{R}^{n \times k}$, $B \in \mathbb{R}^{k \times m}$, $C \in \mathbb{R}^{n \times m}$
Output: $C := C + AB$

1: **for** $i := 1, \ldots, n$ **do**
2: $\quad$ **for** $j := 1, \ldots, m$ **do**
3: $\quad\quad$ **for** $l := 1, \ldots, k$ **do**
4: $\quad\quad\quad C_{ij} := C_{ij} + A_{il} B_{lj}$
5: $\quad\quad$ **end for**
6: $\quad$ **end for**
7: **end for**

c.) The LU decomposition without pivoting:

Input: $A \in \mathbb{R}^{n \times n}$
Output: $LU := A$, A is overwritten by L and U

1: **for** $k = 1, \ldots, n-1$ **do**
2: $\quad A_{k+1:n,k} := A_{k+1:n,k} / A_{k,k}$
3: $\quad A_{k+1:n,k+1:n} := A_{k+1:n,k+1:n} - A_{k+1:n,k} A_{k,k+1:n}$
4: **end for**

d.) Forward substitution $Lx = b$ (Backward substitution is the same):

Input: $L \in \mathbb{R}^{n \times n}$, $b \in \mathbb{R}^n$
Output: $x \in \mathbb{R}^n$, $x = L^{-1}b$, b is overwritten by x

1: $b_1 := b_1 / L_{1,1}$
2: **for** $i := 2, \ldots, n$ **do**
3: $\quad b_i := b_i - L_{i,1:i-1} b_{1:i-1}$
4: $\quad b_i := \frac{b_i}{L_{i,i}}$
5: **end for**

e.) Solving a linear system $Ax = b$, $A \in \mathbb{R}^{n \times n}$, $b \in \mathbb{R}^{n \times n}$ and $x \in \mathbb{R}^{n \times n}$. Use the LU-decomposition from c.) and the forward/backward substitution from d.).

Exercise 3:

Consider the so called vector-triad benchmark:

Input: $a, b, c, d \in \mathbb{R}^n$
Output: $a_i = b_i + c_i d_i \quad \forall\, i = 1 \ldots, n$

1: **for** $i = 1, \ldots, n$ **do**
2: $\quad a_i := b_i + c_i d_i$
3: **end for**

a.) Compute the runtime of the vector-triad when we execute it sequentially on a CPU with a performance of 12.8 GFlops/s for different vector lengths n:

Length n of a, b, c, d	Runtime in s
$n = 10\,000$	
$n = 100\,000$	
$n = 1\,000\,000$	
$n = 100\,000\,000$	

b.) Explain why the practical results are much different from the theoretical ones. What is might be the problem when we analyze the theoretical performance of algorithms in this simple way?

c.) It is obvious that the vector-triad is perfectly parallelizable. Why does even employing a second CPU-core with an additional performance of 12.8 GFlops/s not result in a performance gain?