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**Scientific Computing 1**  
**Handout 7**  
**November 15, 2016**

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**Error Concepts, Stability and Conditioning**

Consider  $y = f(x)$ ,  $x \in D \subset \mathbb{R}^n$ ,  $y \in V \subset \mathbb{R}^m$  and the computed result  $\hat{y} = y + \Delta y = f(x + \Delta x)$

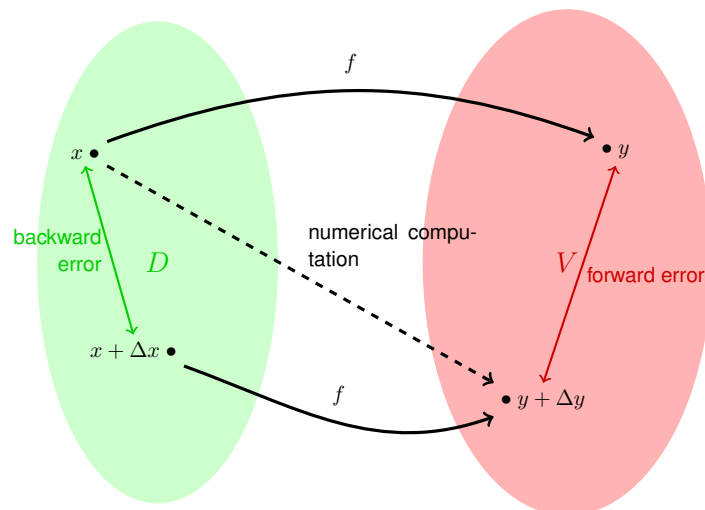


Figure 1: relation of forward and backward errors and numerical computation

• **forward error:**

- *absolute*:  $\|y - \hat{y}\|$ ,
- *relative*:  $\|y - \hat{y}\|/\|y\|$ .

Estimated in a *forward error analysis*.

• **backward error:**

- *absolute*:  $\eta$ ,
- *relative*:  $\eta/\|x\|$ ,

where  $\eta := \inf\{\|\Delta x\| \mid \hat{y} = f(x + \Delta x)\}$ . Estimated in a *backward error analysis*.

- **numerical stability** (of an algorithm):

- An algorithm producing a relative backward error of the magnitude of the relative data errors  $\frac{\|\Delta x\|}{\|x\|}$  is called *(numerically) backward stable*.
- If an algorithm produces relative forward errors of the magnitude a backward stable algorithm would produce, then it is denoted *(numerically) forward stable*.

- **backward stable**  $\Rightarrow$  **forward stable**

- **(relative) condition number:**

$$c(f, x) := \frac{\|x\|}{\|f(x)\|} \|f'(x)\|$$

Depends on problem *and* the data. Mathematical problems are often not generally badly conditioned but conditionally badly conditioned depending on the data.

- $c(f, x) \approx 1 \Rightarrow$  well conditioned
- $c(f, x) \gg 1 \Rightarrow$  badly conditioned
- $c(f, x) \ll 1 \Rightarrow$  possibly bad due to “loss of information”  $\leftrightarrow$  large backward error.

An algorithm can already become unstable if a (well conditioned) problem is subdivided into several steps and only one step is ill conditioned.

- **rule of thumb:**

$$\text{forward error} \approx \text{condition number} \times \text{backward error}$$

- **justification of computational results:**

- good conditioning and stable algorithm  $\Rightarrow$  reliable results
- bad conditioning or unstable algorithm  $\Rightarrow$  unsure results