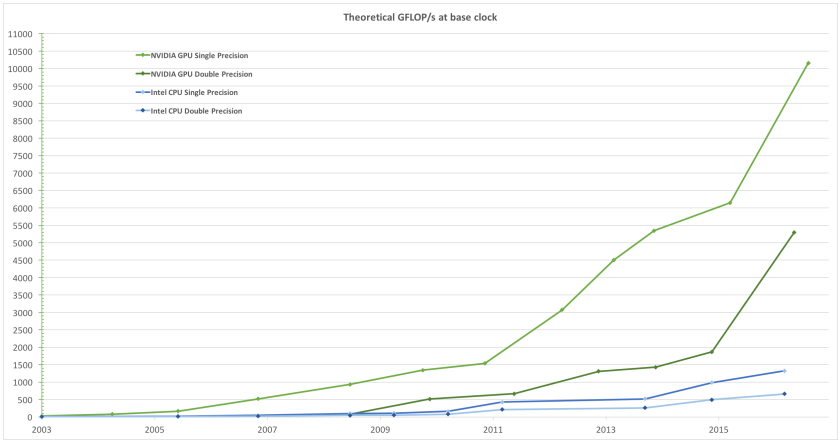
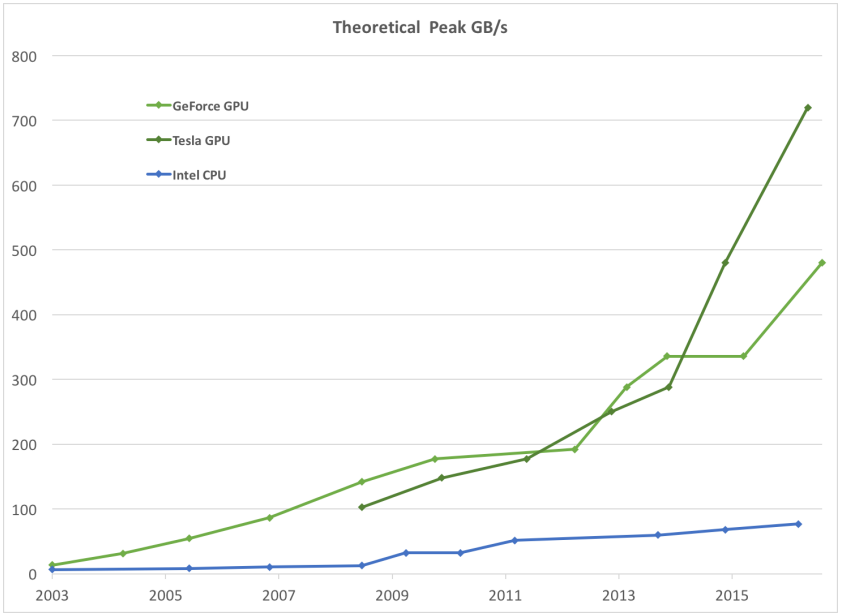
GPU Computing and Accelerators: Part I

Why use accelerators?

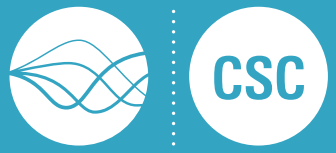


(a) Floating point operations



(b) Memory bandwidth

Figure: Throughput comparison of Multicore CPUs and CUDA enabled GPUs (taken from CUDA C Programming Guide)



Why use accelerators?

Architecture	GFLOPS	GFLOPS/Watt	Utilization
Core i7-960	96	1.14	**95%**
Nvidia® GTX280	410	2.6	66%
Cell	200	5.0	88%
Nvidia® GTX480	**940**	5.4	70%
TI C66x DSP	74	**7.4**	57%

Table: Power efficieny comparison of Multicore CPUs and accelerator chips (taken from Conference Poster by F. Igual and M. Ali)

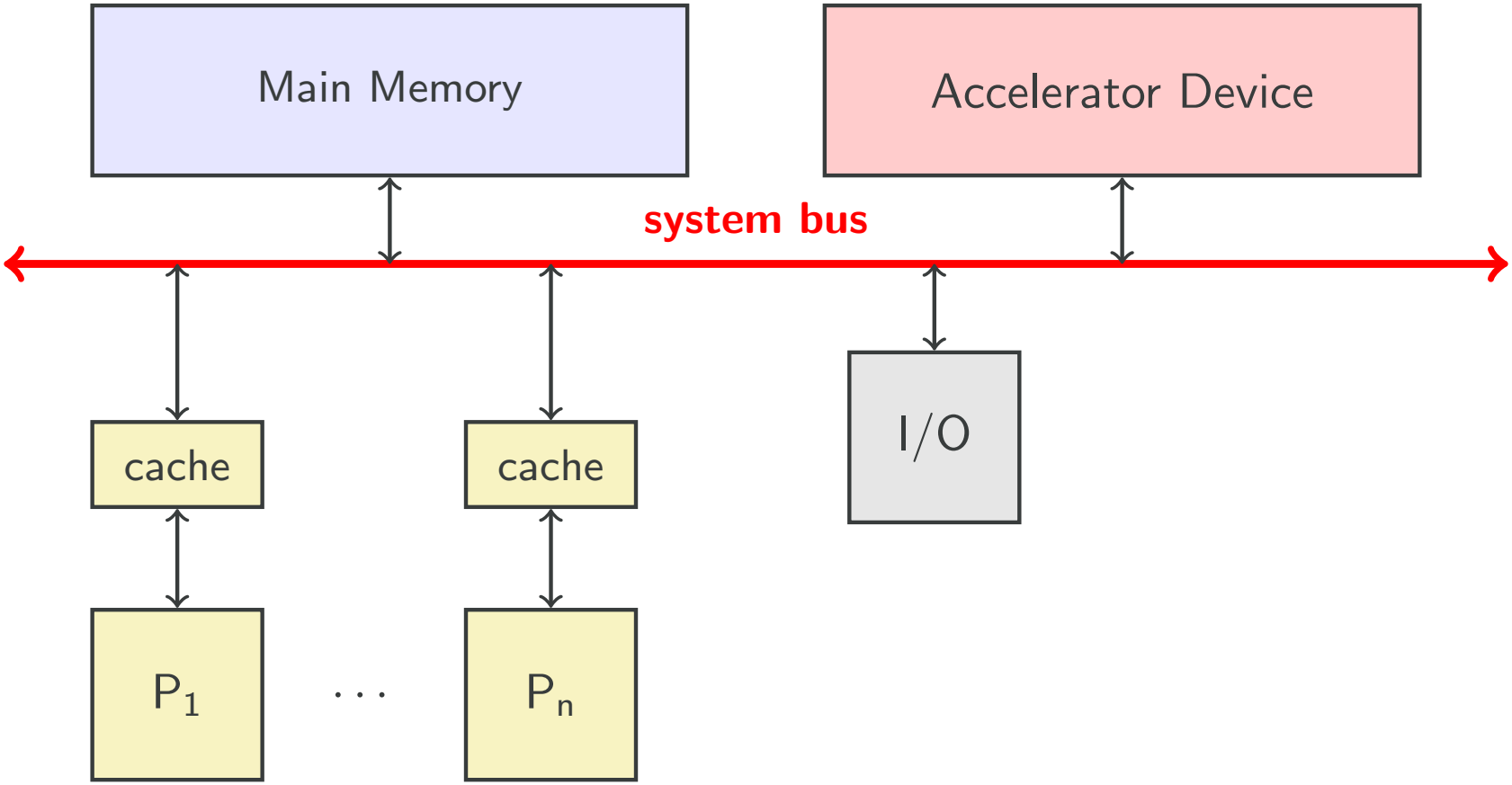


Figure: Schematic of a general parallel system

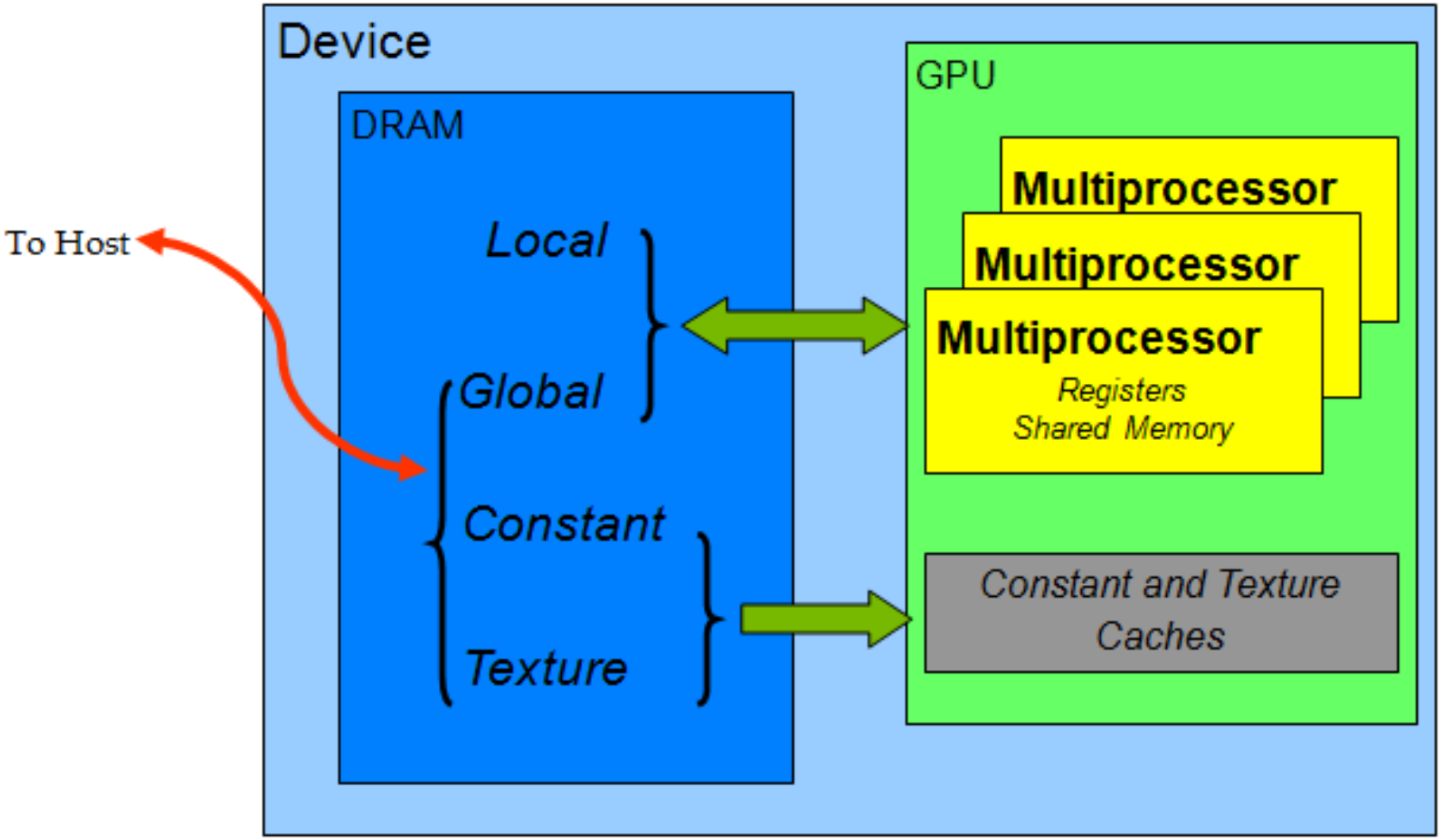


Figure: Memory configuration of a CUDA Device (taken from CUDA C Programming Guide)

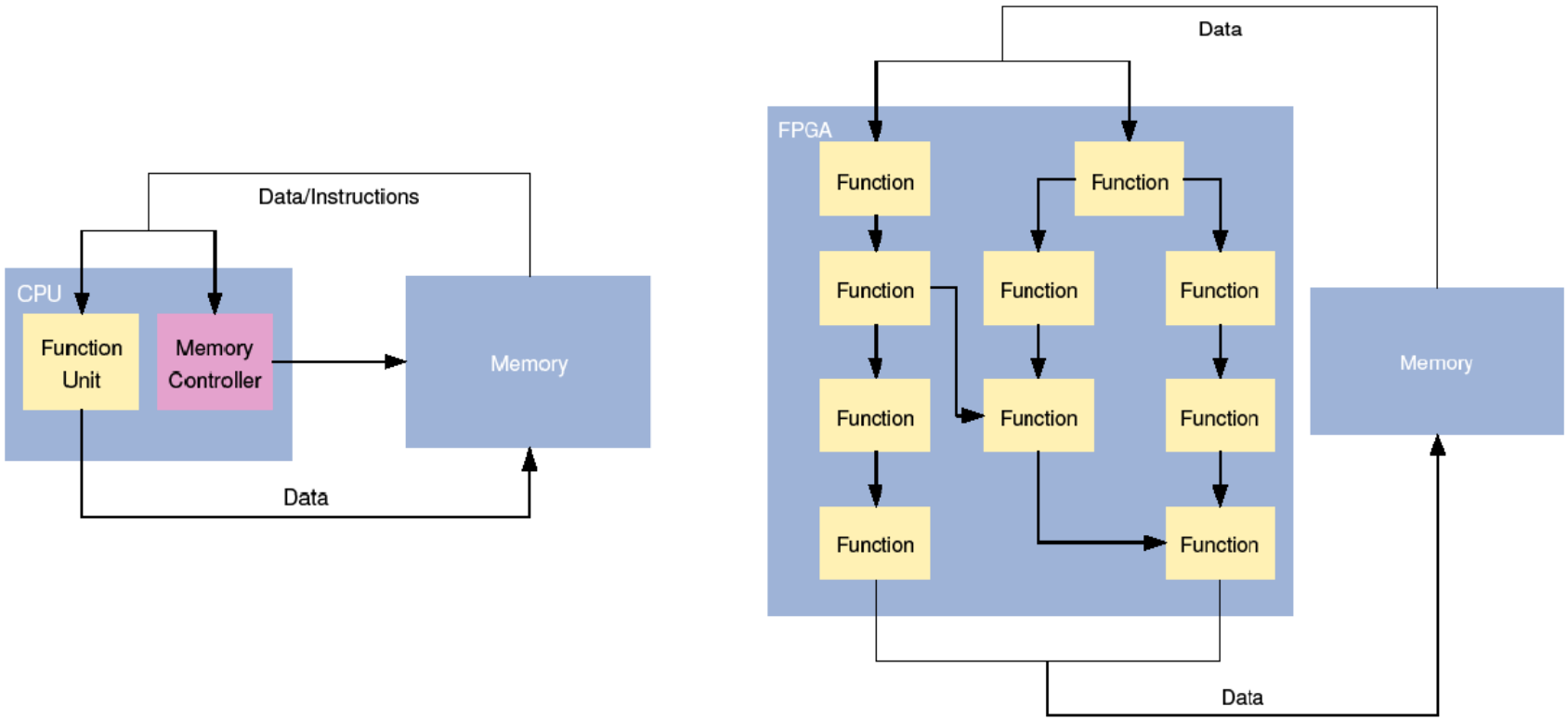


Figure: Comparison of CPUs and FPGA execution models.

GPU Computing and Accelerators: Part II

CUDA is two things at the same time:

1. **platform model**
   for the hardware implementation of general purpose graphics processing units made by the NVIDIA® Corporation.

2. **programming model**
   realizing the software implementation and scheduling of tasks of the parallel programs on the above hardware.

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The number of threads in a warp may depend on the hardware. One finds mostly 32 threads per warp which in turn is the smallest number of tasks executed in SIMD style.

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The grid represents the largest freedom in design that the developer has.

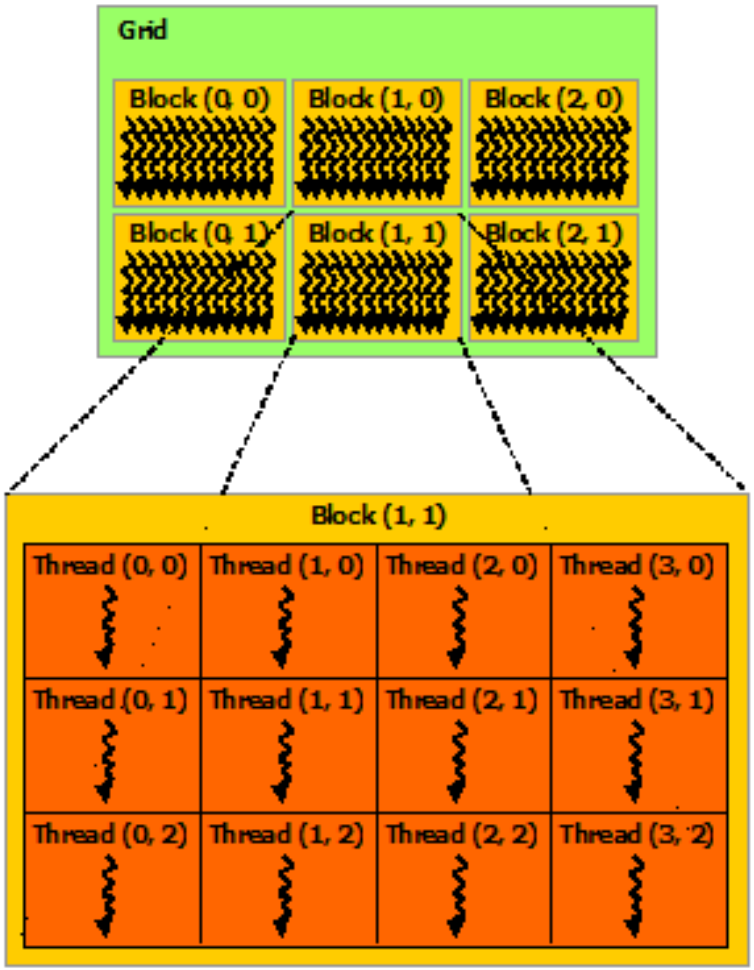

Figure: Grids of Thread Blocks (taken from CUDA C programming guide)

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In case multiple GPUs are installed on a single host system with multiple CPUs, each GPU is connected to a single CPU representing a single NUMA node of the host system.

The host CPU controls the execution of the program. However host and device may execute their tasks asynchronously. When not specified differently data transfers between them serve as implicit synchronization points.

Definition (kernel)

The *kernel* is the core element of a CUDA parallel program. It represents the function that specifies the work a certain thread in a block on a grid has to execute.

We will see in the course of this Chapter how the thread executing the kernel knows which part of the global problem it has to perform.

We will next introduce the most basic elements of the CUDA C language extension. These consist of two important things.

1. **qualifiers** that apply to functions and specify where the function should be executed,
2. **launch size specifiers** that control the grid and block sizes that are used to run a kernel.

An extensive API, defining C-style functions and data types to be used in CUDA programs, together with a handful of libraries for several kinds of tasks (e.g., a BLAS implementation) complete the picture.

Compute Unified Device Architecture (CUDA)

Most Basic Syntax of the CUDA C Extension

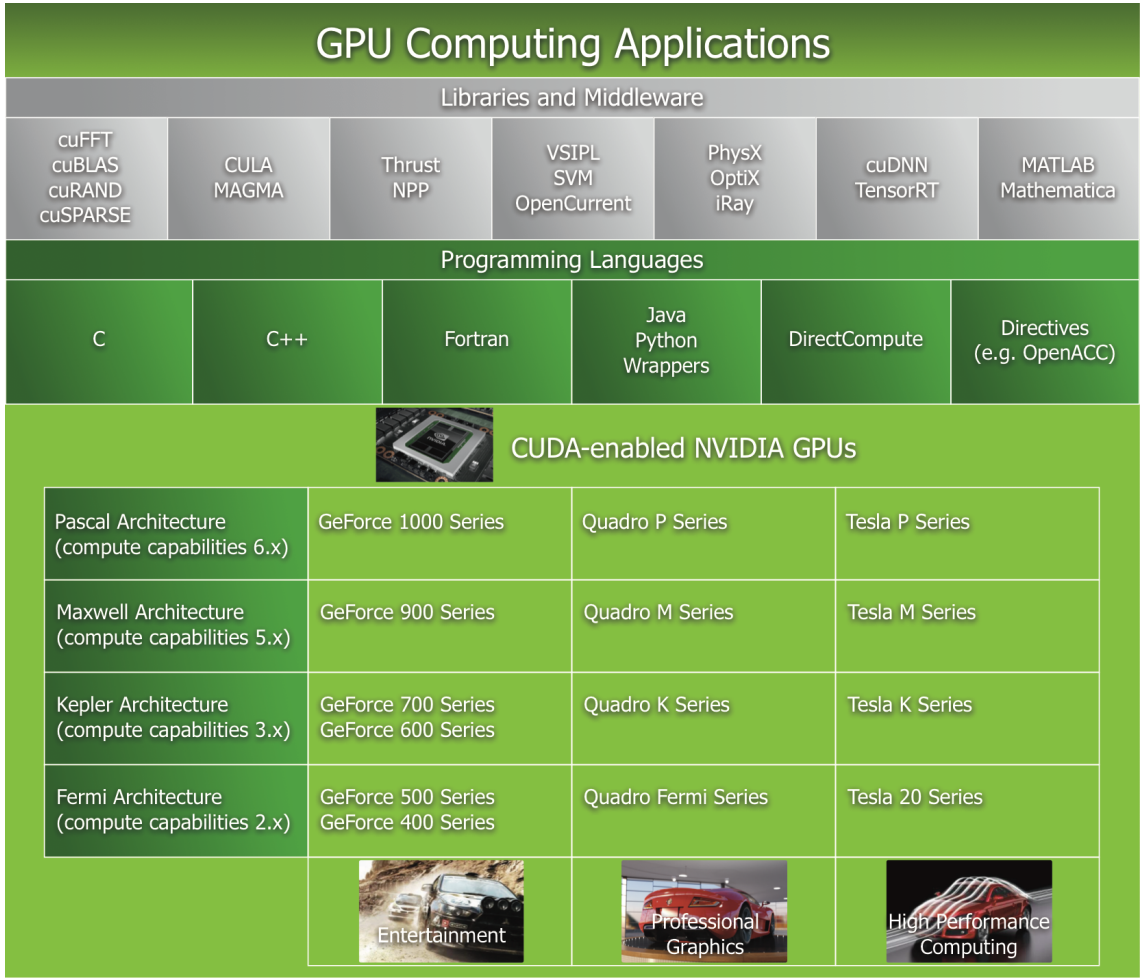

Figure: The CUDA GPU computing applications framework (taken from CUDA C programming guide)

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- `__constant__`applies to a variable specifying the residence in the constant memory.

Note that `__global__` and `__device__` functions are not allowed to be recursive.

The basic launch size specification for a kernel takes the form

```
<<< grid , block size >>>
```

where `grid` specifies the block distribution and `block size` indicates the number of threads per block in the grid.

Example

- `<<<1,1>>>` launches 1 block with 1 thread
- `<<<N,1>>>` launches N blocks with 1 thread each
- `<<<1,N>>>` launches 1 block with N threads
- `<<<N,M>>>` launches a 1d grid of N blocks running M threads each

Both the arguments can be two dimensional distributions. CUDA defines special tuple hiding types for these declarations. Using

```
dim3 grid(3,2)
dim3 threads(16,16)
```

one defines a 3×2 grid of blocks for running 256 threads arranged in a 16×16 local grid. These are then used in the launch specification as

```
<<< grid, threads>>>
```

Launch size specifications are simply appended to the kernel function name upon calling it.

The following examples are taken from the "CUDA by Example" book.

Example

```
#include "../common/book.h"

__global__ void kernel( void ) { }

int main( void ) {
    kernel<<<1,1>>>();
    printf( "Hello, World!\n" );
    return 0;
}
```

Example

```
#include "../common/book.h"

__global__ void add( int a, int b, int *c ) {
    *c = a + b;
}

int main( void ) {
    int c;
    int *dev_c;
    HANDLE_ERROR( cudaMalloc( (void**)&dev_c, sizeof(int) ) );

    add<<<1,1>>>( 2, 7, dev_c );

    HANDLE_ERROR( cudaMemcpy( &c, dev_c, sizeof(int),
                              cudaMemcpyDeviceToHost ) );
    printf( "2 + 7 = %d\n", c );
    HANDLE_ERROR( cudaFree( dev_c ) );

    return 0;
}
```

Example

```
#include "../common/book.h"

__device__ int addem( int a, int b ) {
    return a + b;
}

__global__ void add( int a, int b, int *c ) {
    *c = addem( a, b );
}

int main( void ) {
    int c;
    int *dev_c;
    HANDLE_ERROR( cudaMalloc( (void**)&dev_c, sizeof(int) ) );

    add<<<1,1>>>( 2, 7, dev_c );

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    printf( "2 + 7 = %d\n", c );
    HANDLE_ERROR( cudaFree( dev_c ) );

    return 0;
}
```

In order to be able to compile the previous examples, one needs to check a few prerequisites:

- NVIDIA® device drivers and hardware,
- NVIDIA® CUDA toolkit installation,
- compiler for the host code.

Basic information on CUDA in general can be found at `http://www.nvidia.com/cuda`.

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Regarding the hardware, basically every NVIDIA® GPU released after the appearance of the GeForce 8800 GTX in 2006 is CUDA enabled. However, one needs to make sure that the OS version, the device driver and CUDA Toolkit version are fitting. Working combinations should be available in the toolkits documentation.

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Regarding the compilers NVIDIA® recommends the following

- **Microsoft Windows:** Visual Studio
- **Linux:** Gnu Compiler Collection (GCC)
- **MacOS:** GCC as well via Apple's Xcode

We will in the following restrict ourselves to the Linux world again.

Consider our basic "Hello World!" example is stored in a text file called `hello_world.cu`. Using the `nvcc` compiler provided in the CUDA Toolkit we can compile it by

```
nvcc hello_world.cu
```

Since on Linux `nvcc` uses `gcc` to compile the host code this will also generate a binary called `a.out`. As for `gcc` we can specify the output filename, i.e. name of the resulting executable via

```
nvcc hello_world.cu -o hello_world
```

The file extension `.cu` is used to indicate that we have a C file with CUDA C extensions.

Among the further compiler options we meet many old friends:

- `-c` for generating object files of single `.c` or `.cu` files
- `-g` for generating debug information in the host code
- `-pg` the same for profiling information
- `-O` for specifying the optimization level for the host code
- `-m` specify 32 vs 64bit host architecture

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And we have a few more for the device code, e.g.

`-G` generates debug information for the device code

`-arch` specifies the GPU architecture to be assumed, i.e. the compute capabilities of the device (e.g. `-arch=sm_20`)